

# **Focus Swift:** The First Integrated Mobile High-Accuracy Laser Scanner



#### **FARO®** Focus Swift Techsheet

Fe	at	ur	'es

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Sensor	Range <sup>1</sup>

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90% Reflectivity (white)	0.6 m up to 350 m
10% Reflectivity (dark-gray)	0.6 m up to 150 m
2% Reflectivity (black)	0.6 m up to 50 m

#### **Sensor Information**

Laser Class	1
Wavelength	1550 nm Focus <sup>s</sup> / 905 nm ScanPlan

#### **Sensor Distance Accuracy**<sup>2</sup>

Range Noise	Down to 0.1 mm @10 m 90% (white)
Ranging Accuracy	1 mm

#### **System Performance**

Local Accuracy	2 mm @ 10 m
Global Accuracy <sup>3</sup>	10 mm
Area/Volume <sup>4</sup>	Up to 500 m <sup>2</sup> /5000 m <sup>3</sup> per minute

#### **Data Acquisition Rate**

Field of View (horizontal)

Field of View (vertical)

Max. Measurement Speed	Up to 2 mil. pts/sec (mobile scans)
Deflection Unit	

360°

300°

1 mil. pts/sec (mobile scans)

## **Data Handling and Control**

Data Storage	SDHC™, SDXC™; 32GB; max. 512GB
System Control	Access by mobile devices with HTML5

#### **Color Unit**

Color Resolution	Up to 165-megapixel color
HDR Camera	Exposure bracketing 2x, 3x, 5x
Parallax	Minimized due to co-axial design

### Sensors

IMU	Yes
Dual Axis Compensator	Yes

## **Additional Features**

Digital Hash Function	Scans are cryptographically hashed and signed by the scanner

8.8 kg

340 x 450 x 700 mm

Non-condensing

#### **General Specifications Trolley**

Size Closed (H x W x L)

## Trolley Weight

Size Open (H x W x L)	1080 x 770 x 1370 mm
System <sup>5</sup>	
System Weight (incl. Batteries)	17.5 kg
Max. Size (H x W x L)	1080 x 770 x 2010 mm
Min. Size (H x W x L)	1080 x 770 x 1580 mm
Power Supply Voltages - external	19 V
Power Supply Voltages - internal	14.4 V and 15 V (battery)
Battery Service Life	2 hours
Operating Temperature (ambient)	+5 °C to +40 °C
Extended Operating (ambient) <sup>6</sup>	-10 °C to +40 °C
Storage Temperature (ambient)	Recommended -10 °C to 25 °C Maximum <sup>7</sup> -10 °C to 60 °C

### **Interface Connection**

**Humidity Resistance** 

WLAN	point or client in existing networks	

## Output<sup>8</sup>

Scano Evnort Scan Doints	FARO Scan, FARO Cloud, ASTM E57,
Scene Export Scan Points	.dxf, .igs, .txt, .xyz, .xyb, .pts, .ptz, .pod

Accuracy depends on the effectiveness of the SLAM registration algorithm, which can be influenced by the geometry of the captured environment. Long paths in absence of loop closures, cross passes (and different conditions like narrow corridors or presence of windows/glass walls) can degrade the accuracy. For additional information see tech sheet of Focus<sup>s</sup> / Focus<sup>s</sup> Plus scanners and ScanPlan. All accuracy specifications are one sigma, after warm-up and within operating temperature range; unless otherwise noted. Subject to change without prior notice. Swift is only available for Focus<sup>s</sup> and Focus<sup>s</sup> Plus scanners, requires ScanPlan, accessories and additional FW/SW licenses, requires SCENE version 2020 or higher and Focus firmware 6.6 or higher.

<sup>2</sup> For stationary scans; ranging noise is defined as a standard deviation of values about the best-fit plane for measurement speed of 122,000 points/sec.

<sup>&</sup>lt;sup>1</sup> For a Lambertian scatterer, using Focus<sup>s</sup> 350 or Focus<sup>s</sup> Plus 350

<sup>&</sup>lt;sup>3</sup> In a controlled indoor environment <sup>4</sup> Dependent on scanned environment

<sup>&</sup>lt;sup>5</sup> Including Swift trolley, tripod, mounts, Focus<sup>s</sup> scanner and ScanPlan <sup>6</sup> Low temperature operation: Devices have to be powered on while internal temperature is at or above 15°C

<sup>&</sup>lt;sup>7</sup> Extended storage at temperatures greater than 40°C may degrade battery life and performance

<sup>&</sup>lt;sup>8</sup> Using FARO Scene